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#include <Time.h>
#include <TimeLib.h>

#include <DHT.h>

#include <rgb_lcd.h>
#include <Wire.h>
rgb_lcd lcd;

// Define the pin to which the temphum sensor is connected.
#define DHTPIN1 A0
#define DHTPIN2 A3
#define DHTTYPE DHT22 // DHT 22 (AM2302) pro sensor

// setup temphum sensor
DHT dht1(DHTPIN1, DHTTYPE);
DHT dht2(DHTPIN2, DHTTYPE);

// define display color
const int colorR = 255;
const int colorG = 255;
const int colorB = 255;

//LED array pins
int led1=A1;
//int led2=??;
//peltier pins
int pel11=8;
int pel12=11;
int pel1drive=9;

int pel21=12;
int pel22=13;
int pel2drive=10;

//Set parameters for day night
float tday=15;
float tnight=15;

//Start time
int t0=17;

//Peldrive speed
int speed=50;

void setup()
{
    // set up the LCD's number of columns and rows:
    lcd.begin(16, 2);

    lcd.setRGB(colorR, colorG, colorB);
}

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//peltier elements pin
pinMode(pel11, OUTPUT);
pinMode(pel12, OUTPUT);
pinMode(pel1drive, OUTPUT);
pinMode(pel21, OUTPUT);
pinMode(pel22, OUTPUT);
pinMode(pel2drive, OUTPUT);
//setup LED pins
pinMode(led1,OUTPUT);
//      pinMode(led2,OUTPUT);

//start temphum sensor
dht1.begin();
dht2.begin();

delay(1000);
}

void loop()
{
    float h1 = dht1.readHumidity();
    float t1 = dht1.readTemperature();
    float h2 = dht2.readHumidity();
    float t2 = dht2.readTemperature();

    float del1;
    float del2;

    //get hour of the day
    int tod=(hour()+t0)%24;

    printToLCD(h1, h2, t1, t2, tod);

    // If night
    if (tod<6 || tod>18) {
        //switch off LED arrays
        digitalWrite(led1,HIGH);
//        digitalWrite(led2,HIGH);
        //calculate difference between desired temperature and
measured one (night)
        del1=tnight-t1;
        del2=tnight-t2;
        Serial.print(del1);
        Serial.print(del2);
    }
    else if (tod>=6 && tod<=18) {
        //switch on LED arrays
        digitalWrite(led1,LOW);
//        digitalWrite(led2,HIGH);
        //calculate difference between desired temperature and
measured one (day)
        del1=tday-t1;
        del2=tday-t2;
    }
}

```

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}

//Set Peltier elements to heating or cooling
//chamber1
if (del1<-1){
    //Cooling
    analogWrite(pel1drive,speed);
    digitalWrite(pel11,HIGH);
    digitalWrite(pel12,LOW);
    lcd.setCursor(14, 0);
    lcd.print("C");
}
else if (del1>1){
    //Heating
    analogWrite(pel1drive,speed);
    digitalWrite(pel11,LOW);
    digitalWrite(pel12,HIGH);
    lcd.setCursor(14, 0);
    lcd.print("H");
}
else{
    //Nothing
    analogWrite(pel1drive,0);
    digitalWrite(pel11,LOW);
    digitalWrite(pel12,LOW);
    lcd.setCursor(14, 0);
    lcd.print("-");
}
if (del2<-1){
    //Cooling
    analogWrite(pel2drive,speed);
    digitalWrite(pel21,HIGH);
    digitalWrite(pel22,LOW);
    lcd.setCursor(15, 0);
    lcd.print("C");
}
else if (del2>1){
    //Heating
    analogWrite(pel2drive,speed);
    digitalWrite(pel21,LOW);
    digitalWrite(pel22,HIGH);
    lcd.setCursor(15, 0);
    lcd.print("H");
}
else{
    //Nothing
    analogWrite(pel2drive,0);
    digitalWrite(pel21,LOW);
    digitalWrite(pel22,LOW);
    lcd.setCursor(15, 0);
    lcd.print("-");
}
delay(1000);
}
```

```
//Function to print Information on GOVE LCD
void printToLCD(float h1, float h2, float t1, float t2, float tod)
{
    // set the cursor to column 0, line 1
    // (note: line 1 is the second row, since counting begins with
0):
    lcd.setCursor(0, 0);
    // print the number of seconds since reset:
    lcd.print("T1=");
    lcd.print(round(t1));
    lcd.print("C");
    lcd.print(" H1=");
    lcd.print(round(h1));
    lcd.print("%");

    lcd.setCursor(0, 1);
    // print the number of seconds since reset:
    lcd.print("T2=");
    lcd.print(round(t2));
    lcd.print("C");
    lcd.print(" H2=");
    lcd.print(round(h2));
    lcd.print("%");

    lcd.print(" ");
    lcd.print(tod);
    lcd.print("h");
}
```